# COLLEGE OF ENGINEERING & TECHNOLOGY

#### Module - 8 Theory of Error



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#### Introduction

- Due to faulty instrument, climate condition, and human mistake, it is not possible to measure the observation very precisely.
- Hence the survey measurement have some errors in all measurement.
- Hence the surveyor or civil engineers must know about the errors developed and its elimination.
- Knowledge of theory of error helps a lot to get the correct measurement.



- The errors should be reduced by adopting standard procedure and methods.
- Note that natural errors like wind effect, errors due to earth curvature and refraction due to air can not be controlled by man.



## Types of errors

• There are main three types of the errors.





## Systematic Errors

- Following are the systematic errors which are likely to develop while triangulation.
- 1. Errors due to shrinkage of topographical map.
- 2. Errors by wrong length of chain, may too long or too short.
- 3. Errors due to wrong scale of map.
- 4. Errors caused by atmospheric refraction.
- 5. Errors because of shrinkage or expansion of aria photograph.



- Systematic errors follow some definite mathematical or physical law.
- Determination of correction and its application can be made by definite mathematical or physical law.
- The errors may be positive or negative and the correction are apply.



#### Accidental errors

- The errors which remain as it is even after systematic errors and human mistakes are eliminated called accidental error.
- Accidental errors are also termed as random error or compensating errors.
- These errors are occurs because of the combination of various causes and reasons which would beyond the control and capacity of the surveyor or observer.



# • They do not follow any specific laws and may be positive or negative.

- Accidental errors follows the law of probabilities.
- Accidental errors occur due to lake of perfection in human eyes. Ex: in measurement
- Random errors are generally small and never be avoided in observation.
- The smaller random error the better the precision of the measurement.



#### Human mistakes

- These type of the mistake are caused by the following things
- 1. Improper attention of the observer.
- 2. Carelessness of the observer.
- 3. Poor knowledge of handling the instrument.
- 4. Unskilled and inexperience observer.
- 5. Poor judgment and confusion in the mind of the observer.
- 6. Improper communication between the observer and field party.



#### Definition

**Observation** :-

- $\circ$  The measured numerical value of a quantity is known as observation. Ex: 10m, 10<sup>0</sup>20'20" etc.
- The observation may be classified in to two type :-
- 1. Direct observation
- 2. Indirect observation



- 1. Direct Observations :-
- An observation is called a direct observation if the value of a quantity are measured directly. Ex : measurement of the angle with theodolite.
- 2. Indirect observation
- An observation is called indirect observation when the value of quantity is calculated indirectly from the direct observation.



Observed value of quantity :

- The observed value of quantity is the value obtained from the observation after applying correction.
- The observed value of the quantity may be classified as
- 1. Independent quantity
- 2. Dependent quantity



- 1. Independent quantity :-
- If the value of an observed quantity is independent of the value of the other quantity it is known as independent quantity.
- 2. Dependent quantity :-
- If the value of an observed quantity is depend upon the value of the other quantity it is known as dependent quantity.



#### True value of quantity :-

• The value of quantity free from all the error is known as true value of quantity.

#### True error :-

- The difference between the true value and the observed value is known as true error.
- True error = True Value Observed value
- As the true value can not be find perfectly



□Most probable value :-

- The most probable value of a quantity is the value which has more chance of bring true.
- Most probable value is nearer to the true value

□Most probable error :-

• It may be defined as the quantity which is subtracted from or added to most probable vale of the quantity.



**Residual error :** 

- The difference between the observed value of a quantities and its most probable value is called the residual error.
- Residual error = Observed value most probable value

Observation equation :-

• An observation equation is the relation between the observed quantity and its numerical value.



Conditioned equation :

- An observation equation is the equation expressing the relation between several dependent quantities.
- Ex Triangle equation  $A + B + C = 180^{\circ}$

□ Normal Equation :-

• A normal equation is the one which is formed by multiplying each equation by the coefficient of unknown whose normal equation is to be found by any adding the equation.



#### Laws of Accidental error

- A close examination of the observation a accidental errors law are required.
- Accidental laws of error follow the law of probability.
- This law defines the occurrence of error and can be expressed in terms of equation which is used to compute the probable value.
- Accidental errors always written after the observation quantity with the plus and minus sign.



- The following point may be noted in the normal probabilities curve
- 1. Positive and negative errors are equal in size and frequency, as the curve is symmetrical.
- 2. Small error are more frequent than large error.
- 3. Very large error seldom occur and are impossible.



#### Probable error

- Probable error is measurements is calculated from the probability curve of error.
- In large series of observation the probable error is an error of the observation is greater or less.
- If the probable error of an angular observation is 2 second so the probability of the error between the limit of -2 second to +2 second.



### From the probability of the curve

- 1. Probable error of the single measurement is given by
- Es = ± 0.6745  $\sqrt{\Sigma v^2/n-1}$
- Es = probable error of the single observation
- v = difference between any single observation and mean of the series.
- n = number of the observation in the series



#### Probable error of an average

- Since the average of n observation is the sum of the observation divided by n, the probable error of the average of the n observation is  $\sqrt{n}$ /n times the probable error of single observation.
- Em = Es /  $\sqrt{n}$
- Em = probable error of the mean



#### Probable error of a sum of observation

- Esm =  $\sqrt{E1^1 + E2^2}$  .....
- E1, E2 = probable error of several observation which sum up in measurement.



#### Mean Square Error

• The mean square error is equal to the square root of the arithmetic mean of the individual errors.

• MSE = 
$$\frac{\pm \sqrt{v1^2 + v2^2 + v3^2 + \cdots}}{n}$$

- V1, V2 = Individual error
- n = Number of the observation



#### Average error

• For as series of observation of equal weight, an observation error is defined as the arithmetic mean of separate error, taken all with the same sign either plus or minus.



## Standard Deviation ( $\sigma$ )

- The standard Deviation defined as the
- $\sigma = \pm \sqrt{\Sigma v^2/n 1}$
- Here v = Residual (Variation)
- n = Number of the observation
- The standard deviation is also known as the root mean square error of the measurement.



#### Determine the probable error

- Considering the following cases :
- 1. Direct observation of the equal weights :
- a. Probable error of single observation unit weight.
- b. Probable error of single observation of weight w.
- c. Probable error of single arithmetic mean.



- 2. Direct observation of the unequal weight :
- a. Probable error of single observation unit weight.
- b. Probable error of single observation of weight w.
- c. Probable error of weighted arithmetic mean.



- 3. Indirect observation of independent quantities.
- 4. Indirect observation involving conditional equation.
- 5. Computed quantities.



#### Direct observation of the equal weights

a. Probable error of single observation unit weight may be calculated from the following equation.

• 
$$E_s = \pm 0.06745 \sqrt{\Sigma w v^2/n - 1}$$

Where

• 
$$\Sigma v^2 = v_1^2 + v_2^2 + v_3^2 + \dots$$

• V = Residual error

= Observed value of quantity – Probable value of quantities

• n = Number of observation



 b. Probable error of single observation of weight w may be calculated from the following equation :

$$E_{sw} = E_s / \sqrt{w}$$



c. Probable error of single arithmetic mean may be calculated by the following formula :

$$E_m = E_s / \sqrt{n}$$



# Direct observation of the unequal weight

a. Probable error of single observation unit weight :

$$E_{su} = \pm 0.06745 \sqrt{\Sigma w v^2/n - 1}$$



b. Probable error of single observation of weight w :

$$E_{suw} = E_{su} / \sqrt{n}$$

$$E_{suw} = \pm 0.06745 \sqrt{\Sigma w v^2 / w (n - 1)}$$



#### c. Probable error of weighted arithmetic mean :

$$E_{swm} = \pm 0.6745 \sqrt{\Sigma w v^2 / \Sigma w (n-1)}$$



# Indirect observation of independent quantities

The probable error of an observation of unit weight

$$E_{si} = \pm 0.06745 \sqrt{\Sigma w v^2 / (n - q)}$$

• The probable error of an observation of weight w  $E_{siw} = E_{si} / \sqrt{w}$ 

Here

n = the number of observation equations

q = the number of unknown quantities


# Indirect observation involving conditional equation

• The probable error of an observed unit weight

$$E_{sic} = \pm 0.06745 \sqrt{\Sigma w v^2 / (n - q + p)}$$

Where

- n = number of observation equations
- q = the number of unknown observation
- p = the number of conditional equations



## Laws of Weights

- The weight of the quantities is trust worthiness of a quantities.
- The relative precision and trustworthiness of an observation of an observation as compare to the precision of other quantities is known as weight of the observation.
- The weight are always expressed in number.
- Higher the number higher the precision and trust as compare to lesser number.



- Ex : an observation with a weight 6 is three time precise as an observation with a weight of 2.
- Weights are assigned to the observation or quantities observed in direct proportion to the number of times, the quantities is measured.



### Laws of weight (1)

- The weight of the arithmetic mean of the number of observation of unit weight is equal to the number of observation.
- Ex : calculate the weight of the arithmetic mean of the following observation of an angle of unit weight.

Angle	Weight
60°30'10"	1
60°30'15"	1
60°30'20"	1



• Sol :- here n = 3

Arithmetic mean =  $60^{0}30'10'' + 60^{0}30'15'' + 60^{0}30'20''$ 3 =  $60^{0}30'15''$ The weight of the arithmetic mean  $60^{0}30'15''$  is 3.



### Laws of weight (2)

- The weight of the weighted arithmetic mean of the number of observation is equal to the sum of the individual weights of observation.
- Ex :- an angle A was observed three times as given below with their respective weights. What is the weight of the weighted arithmetic mean of the angle?

Angle	Weight
40°15'10"	1
40°15'14"	2
40°15'12"	3



- Sol :- weighted arithmetic mean of A
   = (40°15'10") X 1 + (40°15'14") X 2 + (40°15'12") X 3
   1+2+3
- $= 40^{0}15'12.33"$
- Sum of the individual weights = 1+2+3 = 6
- The weighted arithmetic mean 40<sup>0</sup>15'12.33" has the weight of 6



#### Laws of weight (3)

- The weight of algebraic sum of two or more quantities is equal to the reciprocal of the sum of the reciprocal of individual weight.
- Ex : calculate the weights of (A + B) and (A B) if the measured values and the weight of A and B respectively are :

 $A = 40^{0}50'30'' \text{ wt. } 3$  $B = 30^{0}40'20'' \text{ wt. } 4$ 



- Sol :
- $A + B = 40^{0}50'30'' + 30^{0}40'20'' = 71^{0}30'50''$
- $A B = 40^{0}50'30'' 30^{0}40'20'' = 10^{0}10'10''$

• The weight of 
$$(A + B)$$
 and  $(A - B)$   
= 1  
 $\frac{1/w_1 + 1/w_2}{= 12/7}$ 

Hence  $A + B = 71^{0}30'50''$  wt. 12/7  $A - B = 10^{0}10'10''$  wt. 12/7



### Laws of weight (4)

- The weight of the any product of the quantities multiplied by a constant is equal to the weight of the quantities divided by the square of that constant.
- Ex :- what is the weight of 3A if A = 30<sup>0</sup>25'40" and its weight is 3?

Sol : -

As A is multiplied by 3, the constant of multiplication C is 3 and weight w of the observation A is 3.



- As per the law 4 the weight of 3 is  $w/c^2$
- Weight of  $3A = 91^{0}17'00'' = 3/3^{2} = 1/3$



### Laws of weight (5)

- The weight of the quantient of any quantity divided by a constant is equal to the weight of that quantities multiplied by the square of that constant.
- Ex :- Compute the weight of A/4 if  $A = 36^{\circ}20'40''$  of weight 3.
- Sol :-

Here constant C = 4



- As per the law no 5
- Weight of  $A/4 = 30^{\circ}20'40''/4 = 3 \times 4^{2}$

 $A/4 = 9^{0}5'10''$  wt. 48



#### Laws of weight (6)

- The weight of an equation remain unchanged if all the sign of the equation are changed or if the equation added to or subtracted from the constant.
- Ex :- If weight of A + B = 76<sup>0</sup>20'30" is 3, what is the weight of - (A + B) or 180<sup>0</sup> - (A + B) ?
- Sol :- from the law 6, the weights of (A + B) will be remain same.

weight of  $-(A + B) = -76^{0}20'30''$  wt. 3 or weight of  $180^{0} - (A + B) = 103^{0}39'30''$  is equal to wt. 3



### Laws of weight (7)

- If an equation is multiplied by its own weight, the weight of the resulting equation is equal to the reciprocal of the weight of that equation.
- Ex :- calculate the weight of the equation <sup>3</sup>/<sub>4</sub>(A + B) if weight of (A + B) is 3/4. The observed value of (A + B) is 120<sup>0</sup>20'40"
- Sol :-

Weight of  $\frac{3}{4}(A + B) = 90^{0}15'30'' = \frac{1}{3}_{4} = \frac{4}{3}$ 



#### Theory of least square

- The principle of distributing errors by the method of least squares is to find the most probable value of quantities.
- The fundamental principle of the method of least square may be stated as follows :-
- In observation of equal precision, the most probable value of the observed quantities are those that render the sum of the square of the residual error a minimum.



- If the measurement are of equal weight, the most probable value is that which makes the sum of the square of the residue (v) a minimum.
- Thus,  $\Sigma v^2 = a \min u$
- If the measurement are of unequal weight, the most probable value is that which makes the sum of the products of the weight (w) and the square of the residuals a minimum.
- Thus,  $\Sigma wv^2 = a \min u$



- When a quantity is being deduced from a series of observation the residual error will be the difference between the adopted value and the several observed values.
- Let  $X_1, X_2, X_3, X_4, \ldots$  Be the observed values
- Z = most probable value
- Then,

 $Z - X_1 = e_1$  $Z - X_2 = e_2$  $Z - X_3 = e_3$ 

.....(1) =

• Where e are the respective residual error of the observed value.



• 
$$M = \frac{X_1 + X_2 + X_3 + \dots + X_n}{n}$$
 .....(2)  
 $M = \Sigma X / n$   
Where n = number of observation  
From equation (1), nZ -  $\Sigma X = \Sigma e$   
 $Z = (\Sigma X/n) + (\Sigma e/n)$   
 $Z = M + (\Sigma e/n)$  ......(3)



- If the number of the observation is large, n is very large and e is kept small by making precise measurement, and the second term (Σe/n) become nearly equal to zero
- Thus Z = M
- Thus when the number of observation is large, the arithmetic is the true value or most probable value.

• Z = M



• Now we calculated the residual error from the mean value. If v<sub>1</sub>, v<sub>2</sub>, v<sub>3</sub> etc. are the residual errors, then

$$M - X_1 = v_1$$
  
 $M - X_2 = v_2$   
 $M - X_3 = v_3$  .....(4)

Adding the above

••••••••••••••



$$nM - \Sigma X = \Sigma v$$
  

$$M = (\Sigma v/n) + (\Sigma X/n)$$
  

$$M = M + (\Sigma v/n)$$
  

$$(\Sigma v/n) = 0$$
 .....(5)

- Hence the sum of residual equals zero and the sum of plus residual equals the sum of minus residuals.
- Let N be any other value of the unknown other than the arithmetic mean, we have







## Rules for giving weight

- The weights of an angle varies directly to the number of observation made on the angle.
- The weights of the level line vary inversely as the length of their route.
- The weight of any angle measured a large number of times, is inversely proportional to the square of the probable error.
- The correction to be applied to various observed quantities are in inversely proportional to their weight.



## Distribution of error to the field observations

- When the observation are made there are some error during the observation.
- It is necessary to check the observation made in the field for the closing error.
- The closing error should be distributed to the observed quantities.



# Rules should be applied for distribution of the error

- 1. The correction to be applied to an observation is inversely proportional to the weight of the observation.(in other word greater weight, the smaller correction)
- 2. The correction to be applied to an observation is directly proportional to the square of the probable error.
- 3. In case of line of levels, the correction to be applied is proportional to the length or route.
- 4. If all the observation are of the same weight, the error is distributed to observed quantities equally.



#### Example : 1

The fooling are three angle observed at a station closing the horizon, along with their probable error of measurement, Determine the correct values.

$$A = 85^{0}13'10'' \pm 2''$$

$$B = 130^{0}49'30'' \pm 3''$$

$$C = 143^{0}57'10'' \pm 4''$$



#### Solution :-

Sum of three angle = 85<sup>0</sup>13'10"  $+ 130^{0}49'30''$  $+ 143^{0}57'10"$ 359°59'50" so here Discrepancy = 10" Here C1, C2, C3 are the correction applied for angle A, B, C etc.



(As per rule no 2)  

$$C_1: C_2: C_3 = (2^2): (3^2): (4^2) = 4:9:16$$
 .....(1)  
 $C_1 + C_2 + C_3 = 15$ ".....(2)

$$C_1: C_2 = 4:9$$
  
 $C_2 = 9/4 C_1$ 

$$C_1 : C_3 = 4 : 16$$
  
 $C_3 = 16/4 C_1 = 4 C_1$ 



Now put the both  $C_2$ ,  $C_3$  value in equation no 2 So

$$C_1 + 4 C_1 + 9/4 C_1 = 15"$$
  
 $C_1 (1 + 4 + 9/4) = 15"$   
 $C_1 = 15 (4/29) = 2.07"$   
 $C_2 = 4 (C_1) = 4(2.07") = 8.28"$   
 $C_3 = 9/4 (C_1) = 9/4 (2.07") = 4.65"$ 



- Check :-
- $C_1 + C_2 + C_3 = 2.07" + 8.28" + 4.65" = 15"$

Hence the corrected angle are :  $85^{0}13'10'' + 2.07''$   $130^{0}49'30'' + 8.28''$  $143^{0}57'10'' + 4.65''$ 

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#### Example : 2

The following are the angles observed at a triangulation traverse along with their probable errors. Determine correct value of angles.

$$A = 64^{0}12'12'' \pm 02''$$

$$B = 50^{0}48'30'' \pm 04''$$

 $C = 64^{0}59'08'' \pm 05''$ 



#### Solution :-

#### Sum of three angle = 64012'12" $+50^{0}48'30''$ $+ 64^{0}59'08"$ 179<sup>0</sup>59'50" so here Discrepancy = 10" Here C1, C2, C3 are the correction applied for angle A, B, C etc.



(As per rule no 2)  

$$C_1: C_2: C_3 = (2^2): (4^2): (5^2) = 4: 16: 25 \dots (1)$$
  
 $C_1 + C_2 + C_3 = 10^{\circ}$ .....(2)

$$C_1 : C_2 = 4 : 16$$
  
 $C_2 = 16/4 C_1 = 4 C_1$ 

$$C_1 : C_3 = 4 : 25$$
  
 $C_3 = 25/4 C_1 = 25/4 C_1$ 



- Check :-
- $C_1 + C_2 + C_3 = 0.89" + 3.56" + 5.55" = 10"$

Hence the corrected angle are :

 $64^{0}12'12'' + 0.89''$  $+ 50^{0}48'30'' + 3.56''$  $+ 64^{0}59'08'' + 5.55''$  $\overline{180^{0}00'00''}$ 





Now put the both 
$$C_2$$
,  $C_3$  value in equation no 2  
So  
 $C_1 + 4 C_1 + 25/4 C_1 = 10$ "  
 $C_1 (1 + 4 + 25/4) = 10$ "  
 $C_1 = 10 (4/45) = 0.89$ "  
 $C_2 = 4 (C_1) = 4(0.89") = 3.56"$   
 $C_3 = 25/4 (C_1) = 25/4 (0.89") = 5.55"$
# Determination of most probable value of quantities

- The most probable value of quantities is the value which has more chance of being true than any other value.
- This value is derived from the several different value.
- The most probable value of a quantities can be determined from the principle of least squares.



In practice, the following cases may arise of which the most probable value may be require to determine

- Direct observation of equal weight
- Direct observation of unequal weight
- Indirect observations involving unknown of equal weight
- Indirect observations involving unknown of unequal weight
- Observation equation accompanied by condition equation



### Case :1 Direct observation of equal weight

- The most probable value of the directly observed quantities of observation of equal weight is the arithmetic mean of the observation.
- Thus if X<sub>1</sub>, X<sub>2</sub>, X<sub>3</sub>, .....X<sub>n</sub> be observed value of a quantities of equal weight and X be the most probable value of that quantities.

• 
$$X = M = (X_1 + X_2 + X_3 + \dots + X_n)$$





- Ex : the following direct measurement of a base line were taken 2523.32m, 2523.25m, 2523.17m, 2523.38m, 2523.47m, 2523.68m, calculate most probable value of the length of the base line.
- Sol :-

• 
$$X = M = (X_1 + X_2 + X_3 + \dots + X_n)$$
  
n



## X = M = 2523.32 + 2523.25 + 2523.17 + 2523.38 + 2523.47 + 2523.68

#### M = 2523.378 m

# The most probable value of a base line length X = 2523.378 m



### Case: 2 Direct observation of unequal weight

- The most probable value of the directly observed quantities of observation of equal weights is the weighted arithmetic mean of the observations.
- Thus if X<sub>1</sub>, X<sub>2</sub>, X<sub>3</sub>, .....X<sub>n</sub> be observed value of a quantities and w<sub>1</sub>, w<sub>2</sub>, w<sub>3</sub>, .....w<sub>n</sub> be their weight, let X be the probable quantities.

$$X = \underbrace{X_1 w_1 + X_2 w_2 + X_3 w_3 + \dots + X_n w_n}_{W_1 + W_2 + W_3 + \dots + W_n}$$



 Ex :- Find the most probable value of the angle from the following observation
A = 76<sup>0</sup>35'00" wt 1

$$A = 76^{0}33'40'' \text{ wt } 2$$

 $X = X_1 w_1 + X_2 w_2 = (76^{0}35'00'') X 1 + (76^{0}33'40'') X 2$  $w_1 + w_2 \qquad 1 + 2$ 

$$= 76^{0}34'6.67"$$

